

Math 2040 C Week 5

Null space and Ranges

Defn 3.12, 3.17 Let $T \in L(V, W)$. Define null space of T and range of T to be

$$\text{null } T = \{v \in V : T(v) = \vec{0}_W\}$$

$$\text{range } T = \{T(v) \in W : v \in V\}$$

Other notations:

$$\text{null } T = \ker T = \text{kernel of } T$$

eg $I: V \rightarrow V$ has $\text{null } I = \{\vec{0}\}$, $\text{range } I = V$

$T_0: V \rightarrow V$ has $\text{null } T_0 = V$, $\text{range } T_0 = \{\vec{0}\}$

eg $D: L(P_n(\mathbb{R}), P_n(\mathbb{R}))$, $Df = f'$

$$\text{null } T = \{c : c \in \mathbb{R}\} = \text{span}\{1\}$$

$$\text{range } T = P_{n-1}(\mathbb{R}) = \text{span}\{1, x, \dots, x^{n-1}\}$$

Prop 3.14, 3.19

Suppose $T \in L(V, W)$. Then

$\text{null } T \subseteq V$ and $\text{range } T \subseteq W$ are subspace

We first prove for $\text{null } T$

① $T(\vec{0}_V) = \vec{0}_W \Rightarrow \vec{0}_V \in \text{null } T$

② Suppose $u, v \in \text{null } T$. Then

$$T(u+v) = T(u) + T(v) = \vec{0}_W + \vec{0}_W = \vec{0}_W$$

$$\therefore u+v \in \text{null } T$$

③ Suppose $v \in \text{null } T$, $\lambda \in \mathbb{F}$, then

$$T(\lambda v) = \lambda T(v) = \lambda \vec{0}_W = \vec{0}_W$$

$$\therefore \lambda v \in \text{null } T$$

$\therefore \text{null } T$ is a subspace of V

For range T :

① $\vec{0}_V \in V \Rightarrow \vec{0}_W = T(\vec{0}_V) \in \text{range } T$

② Suppose $w_1, w_2 \in \text{range } T$. Then $\exists v_1, v_2 \in V$

such that $w_1 = T(v_1), w_2 = T(v_2)$.

$$\therefore w_1 + w_2 = T(v_1) + T(v_2)$$

$$= T(v_1 + v_2) \in \text{range } T$$

③ Suppose $w \in \text{range } T, \lambda \in \mathbb{F}$. Then

$\exists v \in V$ such that $w = T(v)$.

$$\therefore \lambda w = \lambda T(v) = T(\lambda v) \in \text{range } T$$

Hence, $\text{range } T$ is a subspace of W \square

eg (Review) Let $T: \mathbb{R}^4 \rightarrow \mathbb{R}^3$ be defined by

$$T\left(\begin{bmatrix} x_1 \\ \vdots \\ x_4 \end{bmatrix}\right) = A \begin{bmatrix} x_1 \\ \vdots \\ x_4 \end{bmatrix}, \quad A = \begin{bmatrix} 1 & 2 & 1 & 1 \\ 1 & 2 & 2 & 3 \\ 2 & 4 & 3 & 4 \end{bmatrix}$$

We want to find basis of $\text{null } T$ and $\text{range } T$

Note $\begin{bmatrix} x_1 \\ \vdots \\ x_4 \end{bmatrix} \in \text{null } T \Leftrightarrow A \begin{bmatrix} x_1 \\ \vdots \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$

$$\left[\begin{array}{cccc|c} 1 & 2 & 1 & 1 & 0 \\ 1 & 2 & 2 & 3 & 0 \\ 2 & 4 & 3 & 4 & 0 \end{array} \right] \sim \left[\begin{array}{cccc|c} \boxed{1} & 2 & 0 & -1 & 0 \\ 0 & 0 & \boxed{1} & 2 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \textcircled{*}$$

↑ pivot ↘ free

Let $x_2 = s, x_4 = t$

$$\Rightarrow \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -2s+t \\ s \\ -2t \\ t \end{bmatrix} = s \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \end{bmatrix}$$

$$\therefore \text{Basis for null } T : \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \end{bmatrix} \right\}$$

$\textcircled{*}$ has pivot on 1st and 3rd column.

Corresponding columns of A form a basis of $\text{range } T$

$$\therefore \text{Basis of range } T : \left\{ \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \right\}$$

Prop Suppose $T \in \mathcal{L}(V, W)$. Then

① T is injective $\Leftrightarrow \text{null } T = \{\vec{0}_V\}$

② T is surjective $\Leftrightarrow \text{range } T = W$

Pf ② follows from definition

For pf of ①,

(\Rightarrow) Suppose T is injective

$$T(\vec{0}_V) = \vec{0}_W \Rightarrow \{\vec{0}_V\} \subseteq \text{null } T$$

If $v \in \text{null } T$, then $T(v) = \vec{0}_W = T(\vec{0}_V)$

T is injective $\Rightarrow v = \vec{0}_V$

$$\Rightarrow \text{null } T \subseteq \{\vec{0}_V\}$$

$$\therefore \text{null } T = \{\vec{0}_V\}$$

(\Leftarrow) Suppose $\text{null } T = \{\vec{0}_V\}$

If $u, v \in V$ and $T(u) = T(v)$, then

$$T(u-v) = T(u) - T(v) = \vec{0}_W$$

$$\Rightarrow u-v \in \text{null } T = \{\vec{0}_V\}$$

$$\Rightarrow u-v = \vec{0}_V \Rightarrow u=v$$

$\therefore T$ is injective

Prop Let $T \in \mathcal{L}(V, W)$. Then

① If $V = \text{span}\{v_1, \dots, v_n\}$, then

$$\text{range } T = \text{span}\{T(v_1), \dots, T(v_n)\}$$

② If $v_1, \dots, v_n \in V$ are lin. dept,

Then $T(v_1), \dots, T(v_n) \in W$ are lin. dept.

③ If $v_1, \dots, v_n \in V$ are lin. indept, T is injective,

Then $T(v_1), \dots, T(v_n) \in W$ are lin. indept.

Pf Exercise

Thm 3.22 (Fundamental Theorem of Linear Maps)

Suppose $T \in L(V, W)$, $\dim V < \infty$

Then $\dim \text{range } T < \infty$ and

$$\dim V = \dim \text{null } T + \dim \text{range } T$$

Rmk No assumption on $\dim W < \infty$

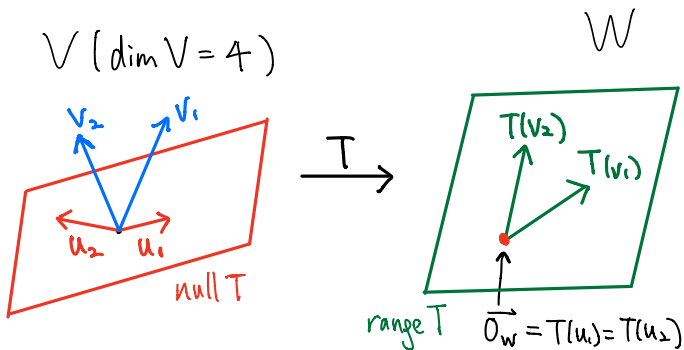
Pf Let $S' = \{u_1, \dots, u_m\}$ be a basis of $\text{null } T$

Extend it to a basis

$$S = \{u_1, \dots, u_m, v_1, \dots, v_n\} \text{ of } V$$

We want to show

$S'' = \{T(v_1), \dots, T(v_n)\}$ is a basis of $\text{range } T$



We first show that $\text{span } S'' = \text{range } T$

Clearly, $T(v_i) \in \text{range } T \quad \forall i=1, 2, \dots, n$

$$\Rightarrow \text{span } S'' \subseteq \text{range } T$$

To show $\text{range } T \subseteq \text{span } S''$, let $w \in \text{range } T$.

Then $w = T(v)$ for some $v \in V$

S is a basis of $V \Rightarrow \exists a_1, \dots, a_m, b_1, \dots, b_n \in \mathbb{F}$

$$\text{s.t. } v = a_1 u_1 + \dots + a_m u_m + b_1 v_1 + \dots + b_n v_n$$

$$= \sum a_i u_i + \sum b_j v_j$$

$$\therefore w = T(v) = T(\sum a_i u_i + \sum b_j v_j)$$

$$= \sum a_i T(u_i) + \sum b_j T(v_j)$$

$$= \sum a_i \vec{0}_w + \sum b_j T(v_j)$$

$$= \sum b_j T(v_j) \in \text{span } S''$$

$$\Rightarrow \text{range } T \subseteq \text{span } S''$$

$$\therefore \text{span } S'' = \text{range } T$$

Next, we show S' is lin. indept.

$$\text{Suppose } c_1 T(v_1) + \dots + c_n T(v_n) = \vec{0}_W$$

$$\text{Then } T(c_1 v_1 + \dots + c_n v_n) = \vec{0}_W$$

$$\Rightarrow c_1 v_1 + \dots + c_n v_n \in \text{null } T$$

S' is a basis of null T

$$\Rightarrow \exists d_1, \dots, d_m \in \mathbb{F} \text{ such that}$$

$$c_1 v_1 + \dots + c_n v_n = d_1 u_1 + \dots + d_m u_m$$

S is lin. indept \Rightarrow all $c_j, d_i = 0$

$$\Rightarrow S'' \text{ is lin. indept}$$

$$\Rightarrow S'' \text{ is a basis of range } T$$

$$\therefore \dim V = |S| = m+n$$

$$= |S'| + |S''|$$

$$= \dim \text{null}(T) + \dim \text{range } T$$

Prop 3.23, 3.24

Let V, W are finite dim. and $T \in L(V, W)$

① If $\dim V > \dim W$, then T is not injective

② If $\dim V < \dim W$, then T is not surjective

Rmk Injectivity/Surjectivity of linear maps are used to compare sizes of vector spaces.

The proposition means that dimension measures the size of vector spaces:

Higher dimensional vector spaces are bigger

Compare:

Fact There is a bijection between \mathbb{R}^2 and \mathbb{R}

$\therefore \mathbb{R}^2$ and \mathbb{R} have same "size" as SETS

Pf The pf makes use of the formula

$$\dim V = \dim \text{null } T + \dim \text{range } T$$

① If $\dim V > \dim W$, then

$$\begin{aligned} \dim \text{null } T &= \dim V - \dim \text{range } T \\ &\geq \dim V - \dim W > 0 \end{aligned}$$

\therefore $\text{range } T$ is a subspace of W

$$\Rightarrow \text{null } T \neq \{0\}$$

$\Rightarrow T$ is not injective

② If $\dim V < \dim W$, then

$$\begin{aligned} \dim \text{range } T &= \dim V - \dim \text{null } T \\ &< \dim W - \dim \text{null } T \\ &< \dim W \end{aligned}$$

$$\Rightarrow \text{range } T \neq W$$

$\Rightarrow T$ is not surjective

eg Let $T: P_2(\mathbb{R}) \rightarrow P_3(\mathbb{R})$ be linear, defined by

$$T(f(x)) = 2f'(x) + \int_0^x 3f(t) dt$$

Is T injective? surjective?

Sol $\dim P_2(\mathbb{R}) = 3 < 4 = \dim P_3(\mathbb{R})$

$\therefore T$ is not surjective.

$$P_2(\mathbb{R}) = \text{span} \{1, x, x^2\}$$

$$\begin{aligned} \Rightarrow \text{range } T &= \text{span} \{T(1), T(x), T(x^2)\} \\ &= \text{span} \left\{ 3x, 2 + \frac{3}{2}x^2, 4x + x^3 \right\} \end{aligned}$$

different degree \Rightarrow lin indept \Rightarrow basis

$$\therefore \dim \text{null } T = \dim P_2(\mathbb{R}) - \dim \text{range } T = 3 - 3 = 0$$

$\therefore \text{null } T = \{0_v\}$ and T is injective.

Prop Suppose $\dim V = \dim W$ is finite, $T \in L(V, W)$

Then T is injective $\iff T$ is surjective $\iff T$ is bijective

Rmk If $V = W$ and $\dim V = \infty$, then

T is injective or surjective $\not\Rightarrow T$ is bijective

Ex Prove

Relation to systems of linear equations

A system of m lin. eqn. of n variables

$$(*) \begin{cases} a_{11}x_1 + \dots + a_{1n}x_n = b_1 \\ \vdots \\ a_{m1}x_1 + \dots + a_{mn}x_n = b_m \end{cases}$$

$$\Leftrightarrow A\vec{x} = \vec{b}, \text{ where } \vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \quad \vec{b} = \begin{bmatrix} b_1 \\ \vdots \\ b_m \end{bmatrix}$$

$$A = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} \in M_{m \times n}(\mathbb{F})$$

Ex Verify $T: \mathbb{F}^n \rightarrow \mathbb{F}^m$, $T(\vec{x}) = A\vec{x}$, is linear

Solve $(*)$ means finding $\vec{x} \in \mathbb{F}^n$ s.t. $A\vec{x} = \vec{b}$

$$\begin{aligned} (*) \text{ has } &\Leftrightarrow \vec{b} \in \text{range } T \\ \text{solution} &= \text{span} \{T(e_1), \dots, T(e_n)\} \\ &= \text{span} \left\{ \begin{bmatrix} a_{11} \\ \vdots \\ a_{m1} \end{bmatrix}, \dots, \begin{bmatrix} a_{1n} \\ \vdots \\ a_{mn} \end{bmatrix} \right\} \\ &= \text{column space of } A \end{aligned}$$

If solution exists,

Solution is unique $\Leftrightarrow T$ is injective

$$\Leftrightarrow \text{null } T = \{0\}$$

\Leftrightarrow the corresponding homogeneous system

$$\begin{cases} a_{11}x_1 + \dots + a_{1n}x_n = 0 \\ \vdots \\ a_{m1}x_1 + \dots + a_{mn}x_n = 0 \end{cases} \text{ has no non-trivial solution}$$

\Leftrightarrow the column vectors of A are lin. indept

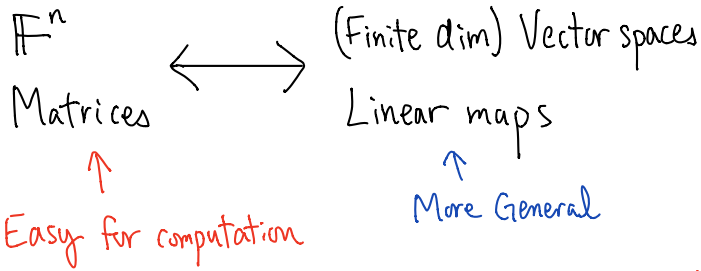
Thm 3.22 \Rightarrow

- number of variables = nullity (A) + rank (A)

Prop 3.23, 3.24 \Rightarrow

- If number of variables $>$ number of equations $(*)$ cannot have unique solution
- If number of variables $<$ number of equations $(*)$ does not have solution for some $\vec{b} \in \mathbb{R}^m$

Matrices and Vector Space, Linear Maps



(eg. Gaussian elimination, determinant, diagonalization)

Want to represent vector spaces and linear maps using matrices.

Defn Let V be a finite dim vector space
An ordered basis of V is a basis of V
with a specific order on its elements.

eg. The standard ordered basis of \mathbb{F}^n

$$\beta = \{e_1, e_2, \dots, e_n\} \quad M(T, \alpha, \beta) \in M_{n \times n}(\mathbb{F}),$$

↑ ↑ ↑
1st 2nd n-th

Rmk ① The notion of ordered basis is used in our reference book (Friedberg).

② In our textbook (Axler), a basis is a list of vectors v_1, v_2, \dots, v_n , which already has a specific order.

With an ordered basis, we can represent a vector in a vector space by a column vector

Defn 3.62

Let $\alpha = \{v_1, \dots, v_n\}$ be an ordered basis of V .
Suppose $v \in V$. Then \exists unique $c_1, \dots, c_n \in \mathbb{F}$
such that $v = c_1 v_1 + \dots + c_n v_n$.

Define the matrix of v with respect to α
to be

$$M(v, \alpha) = \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} \in M_{n \times 1}(\mathbb{F}) \text{ or } \mathbb{F}^n$$

Similarly, for linear maps,

Defn 3.32 Let $T \in \mathcal{L}(V, W)$

$\alpha = \{v_1, \dots, v_n\}$ be an ordered basis of V .

$\beta = \{w_1, \dots, w_m\}$ be an ordered basis of W ,

Define the matrix of T with respect to α, β

to be $M(T, \alpha, \beta) \in M_{m \times n}(F)$, whose

i -th column is $M(T(v_i), \beta)$. i.e.

$$M(T, \alpha, \beta) = \begin{bmatrix} | & & | \\ M(T(v_1), \beta) & \dots & M(T(v_n), \beta) \\ | & & | \end{bmatrix}$$

1st column n-th column

Rmk If the choices of ordered bases are clear,

we write $M(v)$ for $M(v, \alpha)$, $M(T)$ for $M(T, \alpha, \beta)$

Notations in ref. book: $[v]_\alpha$, $[T]_\alpha^\beta$

eg let $T: P_3(\mathbb{R}) \rightarrow P_2(\mathbb{R})$, $T(p(x)) = p'(x)$

$\alpha = \{1, x, x^2, x^3\}$, $\beta = \{1, x, x^2\}$ be basis

of $P_3(\mathbb{R})$ and $P_2(\mathbb{R})$ respectively.

Then $T(1) = 0 = 0 \cdot 1 + 0 \cdot x + 0 \cdot x^2$

$$T(x) = 1 = 1 \cdot 1 + 0 \cdot x + 0 \cdot x^2$$

$$T(x^2) = 2x = 0 \cdot 1 + 2 \cdot x + 0 \cdot x^2$$

$$T(x^3) = 3x^2 = 0 \cdot 1 + 0 \cdot x + 3 \cdot x^2$$

$$M(T(1), \beta) = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad M(T(x), \beta) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$M(T(x^2), \beta) = \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix} \quad M(T(x^3), \beta) = \begin{bmatrix} 0 \\ 0 \\ 3 \end{bmatrix}$$

Hence $M(T, \alpha, \beta) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{bmatrix}$

Formula Let V, W be finite dim,
 α, β be an ordered basis of V, W respectively
 $v_1, v_2 \in V, T_1, T_2 \in L(V, W), \lambda \in \mathbb{F}$. Then

$$\textcircled{1} M(v_1 + v_2) = M(v_1) + M(v_2)$$

$$\textcircled{2} M(\lambda v) = \lambda M(v)$$

$$\textcircled{3} M(T_1 + T_2) = M(T_1) + M(T_2)$$

$$\textcircled{4} M(\lambda T) = \lambda M(T)$$

$$\textcircled{5} M(T(v)) = M(T)M(v)$$

eg Use notation from last eg.

Let $S: P_3(\mathbb{R}) \rightarrow P_2(\mathbb{R})$ $S(p(x)) = p''(x)$

Then

$$M(S) = M(S, \alpha, \beta) = \begin{bmatrix} 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 6 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\therefore M(S+T) = M(S) + M(T) = \begin{bmatrix} 0 & 1 & 2 & 0 \\ 0 & 0 & 2 & 6 \\ 0 & 0 & 0 & 3 \end{bmatrix}$$

Also,

$$\begin{aligned} & M((S+T)(1+x+x^2+x^3)) \\ &= M(S+T) M(1+x+x^2+x^3) \\ &= \begin{bmatrix} 0 & 1 & 2 & 0 \\ 0 & 0 & 2 & 6 \\ 0 & 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 8 \\ 3 \end{bmatrix} \end{aligned}$$

Check:

$$(S+T)(p(x)) = p''(x) + p'(x)$$

$$\therefore (S+T)(1+x+x^2+x^3)$$

$$= (1+2x+3x^2) + (2+6x)$$

$$= 3 + 8x + 3x^2 \quad (\text{Agree with above})$$

Exercise Prove formula $\textcircled{1}$ - $\textcircled{4}$ above.

We will prove $\textcircled{5}$

Recall:

Let $A \in M_{m \times n}(\mathbb{F})$ with columns $v_1, \dots, v_n \in \mathbb{F}^m$
 $B \in M_{n \times k}(\mathbb{F})$ with columns $w_1, \dots, w_k \in \mathbb{F}^n$,

$$c = \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} \in \mathbb{F}^n$$

Then

$$Ac = \begin{bmatrix} | & | & & | \\ v_1 & v_2 & \dots & v_n \\ | & | & & | \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix} = c_1 v_1 + c_2 v_2 + \dots + c_n v_n$$

$$AB = A \begin{bmatrix} | & | & \dots & | \\ w_1 & w_2 & \dots & w_k \\ | & | & & | \end{bmatrix} = \begin{bmatrix} | & | & \dots & | \\ Aw_1 & Aw_2 & \dots & Aw_k \\ | & | & & | \end{bmatrix}$$

eg.

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} = (1) \begin{bmatrix} 1 \\ 4 \end{bmatrix} + (0) \begin{bmatrix} 2 \\ 5 \end{bmatrix} + 2 \begin{bmatrix} 3 \\ 6 \end{bmatrix} = \begin{bmatrix} 7 \\ 16 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 2 & 1 \end{bmatrix} = \begin{bmatrix} 7 & 6 \\ 16 & 15 \end{bmatrix}$$

Pf of ⑤: $M(T(v)) = M(T)M(v)$

Let $\alpha = \{v_1, \dots, v_n\}$, $\beta = \{w_1, \dots, w_m\}$
be ordered basis of V, W resp.

$T \in \mathcal{L}(V, W)$, $v \in V$. Suppose

$$v = c_1 v_1 + \dots + c_n v_n$$

Then

$$\begin{aligned} & M(T(v)) \\ &= M(T(c_1 v_1 + \dots + c_n v_n)) \\ &= M(c_1 T(v_1) + \dots + c_n T(v_n)) \\ &= c_1 M(T(v_1)) + \dots + c_n M(T(v_n)) \\ &= \begin{bmatrix} | & & | \\ M(T(v_1)) & \dots & M(T(v_n)) \\ | & & | \end{bmatrix} \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} \\ &= M(T)M(v) \end{aligned}$$

Prop 3.43 Let $T \in L(U, V)$, $S \in L(V, W)$

α, β, γ be ordered basis of U, V, W resp. Then

$$M(ST, \alpha, \gamma) = M(S, \beta, \gamma) M(T, \alpha, \beta)$$

i.e $M(ST) = M(S)M(T)$

Pf Let $\alpha = \{u_1, \dots, u_k\}$

Then

$$\begin{aligned} M(ST(u_i)) &= M(S(T(u_i))) \\ &= M(S)M(T(u_i)) \\ &= M(S)M(T)M(u_i) \\ &= \underbrace{M(S)M(T)} e_i \end{aligned}$$

\uparrow
i-th column
of $M(ST)$

i-th column of $M(S)M(T)$ $\leftarrow e_i \in \mathbb{F}^k$

$\therefore M(ST) = M(S)M(T)$

eg Let $\alpha = \{1, x, x^2, x^3\}$

$D: P_3(\mathbb{R}) \rightarrow P_3(\mathbb{R})$ be $Dp = p'$.

Then $M(D, \alpha) = M(D) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

Then

$$M(D^2) = M(D)^2 = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}^2 = \begin{bmatrix} 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 6 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$M(D^3) = M(D)^3 = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}^3 = \begin{bmatrix} 0 & 0 & 0 & 6 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$M(D^4) = M(D)^4 = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}^4 = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Note $D^4 = T_0 =$ zero transformation